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This book presents the most recent research advances in robot manipulators. It offers a complete survey to the kinematic and dynamic modelling, simulation, computer vision, software engineering, optimization and design of control algorithms applied for robotic systems. It is devoted for a large scale of applications, such as manufacturing, manipulation, medicine and automation. Several control methods are included such as optimal, adaptive, robust, force, fuzzy and neural network control strategies. The trajectory planning is discussed in details for point-to-point and path motions control. The results in obtained in this book are expected to be of great interest for

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researchers, engineers, scientists and students, in engineering studies and industrial sectors related to robot modelling, design, control, and application. The book also details theoretical, mathematical and practical requirements for mathematicians and control engineers. It surveys recent techniques in modelling, computer simulation and implementation of advanced and intelligent controllers.

Principal authors: U. Kroszynski, B.

Palstr9Sm 1.1 The evolution of concepts and specifications for CAD data exchange The CAD/CAM community has witnessed, during the last decade, the appearance of several specifications as well as proposals for standards which either attempt to cover wider areas or to be more reliable and stable than the others. With the rapid evolution of both hardware and software, the capabilities offered by CAD systems and CAD based application systems are far more advanced than they were only ten years ago, even when they are now based on micro-computers or personal computers. The situation with standards, however, is not and cannot be so. In order to be reliable and accepted by a wide community of both vendors and users, a standard has to be stable. This implies a life span of at least a decade. This also implies that the standard has to be general and flexible enough to accommodate present as well as expected future developments. 1.1.1

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IGES The initial development of concepts for CAD data exchange is strongly influenced by the US Integrated Computer Aided Manufacturing (ICAM) programme, that dealt with the development of methods for data exchange. In September 1979, a subgroup was established with participation of the National Bureau of Standards, the General Electric Company, and the Boeing Company. The result of this effort was the Initial Graphics Exchange Specification (IGES) that was published as a NBS report [61] in 1980.

Robotics is a modern interdisciplinary field that has emerged from the marriage of computerized numerical control and remote manipulation. Today's robotic systems have intelligence features, and are able to perform dexterous and intelligent human-like actions through appropriate combination of learning, perception, planning, decision making and control. This book presents advanced concepts, techniques and applications reflecting the experience of a wide group of specialists in the field. Topics include: kinematics, dynamics, path planning and tracking, control, mobile robotics, navigation, robot programming, and sophisticated applications in the manufacturing, medical, and other areas.

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How to use industry standards to create complete, consistent, and accurate equipment inventories The National Institute of Science and Technology estimates that the loss of information between the construction of buildings and their operation and maintenance costs facility owners \$15.8 billion every year. This phenomenal loss is caused by inconsistent standards for capturing information about facilities and their equipment. In *Equipment Inventories for Owners and Facility Managers*, Robert Keady draws on his twenty+ years of experience in facility management and his intimate knowledge of CSI classification systems and standards to tackle this problem head-on. Using standards already in use in the AEC industry, he provides the road map for capturing everything owners and facility managers need to know to operate and maintain any facility. This comprehensive, step-by-step guide: Explains the different types of equipment inventories and why they are important Identifies and describes the types of information that should be captured in an equipment inventory Describes and compares the different industry standards (CSI OmniClass™ and UniFormat™; COBie; and SPie) that can be used for equipment inventories Provides best practices for identifying and tagging equipment Walks through the equipment inventory process with real-world examples and best practices

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Provides the tools for conducting the equipment inventory—tables of all the possible information and data that need to be collected, and fifty maps of workflows that can be used to capture that data immediately

Advanced modeling techniques are a necessary tool in order to design and manage manufacturing systems effectively. This book contains a set of tutorial chapters on topics ranging from aggregate production planning to real time control, including predictive and reactive scheduling, flow management in assembly systems, simulation of robotic cells, design of manufacturing systems under uncertainty and a historical perspective on production management philosophies. The book will be of interest both to researchers and practitioners, including graduate students in Manufacturing Engineering and Operations Research.

The 26 papers in this volume cover: catchment treatment and reservoir sediment ation; de-silting and silt disposal; modelling techniques; hydraulic design considerations; and mechanical design and material technology.

Very Good, No Highlights or Markup, all pages are intact.

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